DIGITAL EQUIPMENT CORPORATION
MAYNARD, MASSACHUSETTS

ENGINEERING SPECIFICATION

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TITLE KL8/E Asynchronous Data Control (M8650)

REVISIONS

REV	DESCRIPTION	CHG NO	ORIG	DATE	APPD BY	DATE

Abstract

The KL8/E is a single line asynchronous data control for the PDP8-E. A variety of speeds are offered and split lugs are provided such that any desired device codes may be wired in. Factory wiring provides the standard console teleprinter device codes 03 and 04. Both 20 milliampere and EIA/CCITT levels are offered at 110 baud. In the higher speed ranges, only EIA/CCITT interface is offered. The EIA/CCITT interface applies to data leads only; no modem control is provided. This specification includes a complete discussion of the current driver capabilities, the selection of device codes, the selection of speeds, and the configurations available under each option designation.

ENG	APPD	SIZE	CODE	NUMBER	REV
John E. McNamara	John E. McNamara	A	SP	KL8-E-1	

DEC FORM NO. DRA 107

ENGINEERING SPECIFICATION — CONTINUATION SHEET

TITLE KL8/E Asynchronous Data Control

I. General Description

The KL8/E provides complete facilities for interfacing an asynchronous device such as a teleprinter or display to the PDP8/E. Split lugs are provided such that a KL8/E may be assigned any two device codes desired. In this manner a quantity of KL8/E units may be used on a single PDP8/E to provide a multiple teleprinter capability. The instruction set is similar to that used on previous Family-of-8 console teleprinter controls and asynchronous data controls. Several different clock speed and interface options are offered.

II. Physical

The KL8/E is a single quad board which plugs directly into the Omnibus. The same etched board (M8650) is used for all KL8/E options listed below, with a crystal change or cable change determining the option designation applicable.

III. Options

The KL8/E is available in the following options:

Designation	Receive Speed	Transmit Speed	Interface Type	(Board Type)
KL8/E	110 Baud	110 Baud	20 milliampere	M8650
KL8/EA	110 Baud	110 Baud	EIA Data Leads	M8650
KL8/EB	150 Baud	150 Baud	EIA Data Leads	M8650 YA
KL8/EC	300 Baud	300 Baud	EIA Data Leads	M8650 YA
KL8/ED	600 Baud	600 Baud	EIA Data Leads	M8650 YA
KL8/EE	1200 Baud	1200 Baud	EIA Data Leads	M8650 YA
KL8/EF	150 Baud	1200 Baud	EIA Data Leads	M8650 YA
KL8/EG	150 Baud	2400 Baud	EIA Data Leads	M8650 YA

The M8650 and M8650 YA boards use an identical etched board, but differ in their parts lists. The M8650 uses a DEC Part # 18-09880-01 14.418 MHz crystal, while the M8650 YA uses a DEC Part # 18-09880-02 19.661 MHz crystal. The 14.418 MHz crystal is used to obtain the 110 baud frequency, while the 19.661 MHz crystal is used to obtain the 150, 300, 600, 1200, and 2400 baud frequencies. This means that if one desires to change speeds in the field, a crystal change is involved to change to or from the 110 baud speed, plus re-labelling the board handle. To change amongst the speeds that are multiples of 150 baud, only jumper changes are involved.

SIZE	CODE	NUMBER	REV
A	SP	KL8-E-1	

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Both the M8650 and M8650 YA boards contain the appropriate circuitry for both 20 milliampere and EIA operation. A noise suppression network in the 20 milliampere circuitry protects against high frequency noise, but in so doing limits the operating speed of the 20 milliampere interface to 110 baud. The 20 milliampere circuitry is automatically connected when the 7008360 interface cable assembly supplied with the KL8/E option is connected to the board. This cable terminates in a Mate-N-Lock connector compatible with PDP8/E teleprinters, PDP-11 teleprinters, and Mate-N-Lock equipped PDP-15 teleprinters. In like manner, the EIA interface circuitry is automatically connected when the BC01V cable assembly (or BC05C) supplied with the KL8/EA, EB,EC,ED,EE,EF, and EG options is connected. (See Section X)

The EIA interface circuitry meets all present requirements of EIA Specification RS232-C and CCITT Recommendation V24, but interfaces the DATA LEADS ONLY. No modem control is supplied - Data Terminal Ready and Request To Send are held asserted. Use of these options on modems arranged for automatic origination or automatic answering of dial telephone calls is not recommended. The EIA interfaces provided are intended for use with private(non-switched) wire modems operated on a full duplex basis or with a Null Modem (H308 or H312) and a terminal with an EIA interface.

IV. Specifications - Environment

Temperature: Ø degrees to 55 degrees C (Operating)
Humidity: 10% to 90% non-condensing (Operating)

During storage, temperature extremes of -15 degrees C and +65 degrees C can be tolerated.

V. Specifications - Communications Variables

A. Type or Transmission: Asynchronous
Type of Reception: Asynchronous

B. Number of Start Elements Per Character: One

C. Number of Data Elements Per Character: Eight

D. Number of Stop Elements Per Character: One or Two (Jumper selectable on board. Unless otherwise specified, the KL8/E and KL8/EA options will be supplied jumpered for two stop elements and all other options will be supplied jumpered for one stop element.)

E. Receiver Sample Rate: 16 times the baud rate

F. Capabilities of the 20 milliampere driver:

For current calculation purposes, the driver circuit may be envisioned as one lead returned through 750 ohms to -15 volts and the other lead as going to a point connected to -15 through 1 K and to +5 through a 6534D PNP transistor, the state of which is controlled by the KL8/E transmitter circuitry. If one assumes a maximum voltage drop across the transistor when saturated as 1 volt and a minimum potential difference between -15 and +5 of 19.75 volts, the output circuit may be envisioned as an 18.75 volt source in series with a 750 ohm resistor, or at worst a 788 ohm resistor. This arrangement would deliver 24 milliamperes in the short circuit case and would tolerate 150 additional ohms for resistance of the teleprinter magnet circuit and the wiring to the teleprinter magnet. The following wire resistances may be of assistance: (Annealed copper wire, 20 degrees C)

26 AWG : 40.81 ohms/1000 feet
24 AWG : 25.67 ohms/1000 feet
22 AWG : 16.14 ohms/1000 feet
19 AWG : 8.05 ohms/1000 feet

In calculating permissable loop length, remember that the above figures are for one conductor only. You must measure the distance from the KL8/E to the teleprinter AND BACK to obtain a footage distance for use in the above calculation. In addition, certain environmental influences such as radio interference, transformers, possibility of physical damage, etc. may cause the maximum operating distance to be less than that indicated by simple resistive calculations. Extreme caution should be used in any installation over 1500 feet.

G. Capabilities of the 20 milliampere receiver:

For current calculation purposes, the receiver circuit may be envisioned as one lead returned through 560 ohms to -15 volts and the other lead returned to both +5 through 750 ohms and to a -.7 volt diode drop through 82 ohms. The resultant current will be 21 milliamperes for a zero ohm resistance loop to the keyboard contacts and 18 milliamperes in the case of a 150 ohm loop such as that mentioned in Section V-F above. Intermediate values can be determined from straight line interpolation between these points. It is not recommended that contact currents less than 18 milliamperes be used.

The 20 milliampere current receiving circuitry contains

an integrator circuit that may be modelled as a capacitor in series with 402 ohms. The standard value for this capacitor is .47 mfd. This arrangement assists in providing noise reduction by integrating high frequency noise such that its amplitude is insufficient to operate the Schmidt Trigger circuit that follows the integrator. Unfortunately, the integration reduces the rate-of-rise of signals, introducing an additional 2% distortion to the received signal at 110 baud. The high sampling rate of the receiver (16 times the baud rate) makes this additional distortion inconsequential except in the case of very extreme distortion already being present in the received signals. At speeds greater than 110 baud, EIA interface circuitry is used, bypassing both the 20 milliampere integrator circuit and the 20 milliampere Schmidt Trigger circuit.

Should it be desired to operate in current loop mode at speeds greater than 110 baud, the .47 mfd capacitor should be reduced in size by the same proportion as the speed is increased; i.e. if you double the speed, halve the value of the capacitor. This product is not specified to operate in current loop mode at speeds greater than 110 baud and the suggestions given above should not be construed as a commitment on the part of Digital Equipment Corporation to make this product operate in current loop mode at any speed other than 110 baud.

H. Capabilities of the Reader Run Control:

For current calculation purposes, this circuitry may be modelled as one lead being connected to -15 through 180 ohms and the other lead connected to +5 through a 6534D PNP transistor and a 150 ohm resistor. Due to the presence of diode clamps, transistor voltage drop, etc., this second lead may be envisioned as being connected to a + 7/10ths volt source or floating, depending upon the state of the 6534D transistor. The circuit formed by the above elements may be considered as a 14 volt source in series with 180 ohms.

The reader run leads operate a Wheelock #30002 reed relay mounted on a DEC 4915 teleprinter reader control card mounted within the call control area of the Teletype.* This relay has a coil resistance of 920 ohms and is specified to operate by the time the voltage across its coil reaches 9.6 volts. There is a ± 10% tolerance on coil resistance, so a worst case current of 12 milliamperes is required to achieve 9.6 volts across 828 ohms. The 12 milliamperes would cause a 2.3 volt drop across the 180 ohm resistor if that resistor were at the 189 ohm extreme of its ± 5% specification. This means that no more than 14.0 - 11.9 = 2.1 volts can

* "Teletype" is a registered trademark of Teletype Corporation, Skokie, Ill. USA

be dropped by the passage of 12 milliamperes through the wiring to the reader run. That sets a resistance limit of 175 ohms for the reader run control wiring from the KL8/E to the Teletype (and back). (See Section X)

I. EIA Signals Provided

Circuitry on the M8650 and M8650 YA modules conditions the transmitted data and received data to the specifications of Electronic Industries Association (EIA) Specification RS 232 C and Committe Consultatif International Telephonique et Telegraphique (CCITT) Recommendation V24.

The signals and their assigned pins on the 40 pin header found on the M8650 are as follows:

Protective Ground	UU	
Send Data	F	
Receive Data	J	
Request To Send	V	(Held Asserted)
Signal Ground	VV	
Data Terminal Ready	DD	(Held Asserted)

Assertion of the Request To Send lead is required with such modems as the Bell System 103F to maintain them in Full Duplex transmission mode on a private (non-switched) line.

Assertion of the Data Terminal Ready lead is required with such modems as the Bell System 103A to maintain an established dial-up connection.

Note that, since the Request To Send lead is held true, the M8650 and M8650 YA are suitable ONLY FOR FULL DUPLEX OPERATION (An additional reason is that there is no interlocking logic in the M8650 and M8650 YA to make the transmitter and receiver dependent upon each other in the fashion that Half Duplex would require).

Note further that, since Data Terminal Ready is held true, the M8650 and M8650 YA are suitable for dial telephone connection use (such as with the Bell System 103A) ONLY UNDER MANUAL CONTROL. In other words, these modules should not be used in dial telephone connections arranged for the automatic origination of calls or arranged for the automatic answering of calls. The reason for this is that Data Terminal Ready must be negated for a dial-up connection to be dropped when the call is over and the M8650 and M8650 YA are incapable of doing this. In addition, they do not monitor the leads necessary to tell them when to take such action.

In summary, the KL8/E, EA, EB, EC, ED, EE, EF, and EG do not have modem control. Thus, their use with modems is limited to full duplex private line and manual use on the dial-up telephone network.

J. Capabilities of the EIA interface

Total cable length from the KL8/EA(EB, EC,etc) to the associated modem or terminal must not exceed 50 feet under any circumstances.

K. Use With EIA Interface Terminals

The BC01V and BC05C cable assemblies end in male 25 pin connectors in accordance with the EIA specification requirements for data terminal equipment. Likewise, most terminals that have EIA interfaces also employ male 25 pin connectors, as they too are data terminal equipment in the language of the EIA specification.

The EIA specification, in specifying male connectors for data terminal equipment, envisions that each piece of data terminal equipment will be connected to a piece of data communications equipment. The typical connection which the specification envisions is data terminal equipment - modem-communications facility - modem - data terminal equipment. Thus, to stay within the specification when connecting a piece of data terminal equipment to another piece of data terminal equipment, one must introduce the modem-communications facility-modem link. In cases where the two terminals are more than 50 feet apart this would be done with real modems and a real communications facility. Where distances less than fifty feet are involved, Digital Equipment Corporation has devices called Null Modems which contain a female 25 pin connector,a length of cable that transposes the transmitted an received data leads such as a communications facility would,and a second female connector at the opposite end. Use of the Null Modem (H312 or H308) permits the same cables and other hardware to be used for both local and remote terminal applications.

Should a null modem not be available in a VT06 installation, the male/male cord supplied with the VT06 could be removed and the BC01V plugged directly into the female receptacle on the VT06 provided that the following lead swaps are made in the BC01V by swapping pins in the forty pin connector: Swap F & J; Move V to BB.

The above pin changes are not recommended as a general thing, as they result in non-standard cables.

VI. Programming

The KL8/E uses an augmented version of the instruction set used on Family-of-8 console teleprinters and teleprinter controls such as the PT08.

The instruction set is as follows:

6XX0 Clear Keyboard Flag (KCF)

Clears the keyboard flag without setting the reader run flip-flop. The AC is not cleared by this instruction.

6XX1 Skip on Keyboard Flag (KSF)

Increments the contents of the Program Counter if the keyboard flag is set,so that the next sequential instruction is skipped.

6XX2 Clear Keyboard Flag (KCC)

Clears the keyboard flag and AC and sets the reader run flip-flop. This action allows the hardware to begin assembling the next input character in the TTI register. If the reader is activated and there is tape in the reader, a serial character is read from the tape and is assembled in the TTI register. The keyboard can also load characters into the TTI register provided that the reader is deactivated. In either case, the keyboard flag is set when the character is assembled in the TTI register.

6XX4 Read Keyboard Buffer Static (KRS)

ORs the contents of the TTI register with AC4 through 11, and leaves the result in AC4-11. This is termed a static command because neither the AC nor the keyboard flag is cleared.

6XX5 Set/Clear Interrupt Enable (KIE)

Sets or clears the interrupt enable flip-flop as determined by AC11. If AC11 is asserted, an interrupt request will be generated when the KL8/E keyboard or teleprinter flag is set. If AC11 is negated interrupt requests cannot be generated.

6XX6 Read Keyboard Buffer Dynamic (KRB)

Performs the combined operations of the KCC and KRS instructions. Clears the AC and keyboard flag and transfers the contents of the TTI register to AC4 through AC11. This instruction also sets the reader run flip-flop to begin assembly of another character in the TTI register. When this operation is complete, the keyboard flag is set to indicate that another character is available.

The computer clears all flags which are on the clear flags bus (including both the keyboard flag and the reader run enable) when the console CLEAR pushbutton is depressed or when a Clear All Flags instruction is given. This means that the user program must set the reader enable by means of a KCC or KRB instruction before the first input data can be received from the reader. After the first character is assembled, the KRB instructions used to read that character and the succeeding characters will operate the reader appropriately.

6YY0 Set Teleprinter Flag (TFL)

Sets the teleprinter flag to ready the logic for another character.

6YY1 Skip on Teleprinter Flag (TSF)

If the teleprinter flag is set, increments the contents of the program counter by one so that the next sequential instruction will be skipped.

6YY2 Clear Teleprinter Flag (TCF)

Clears the teleprinter flag. This instruction can be microprogrammed with TPC.

6YY4 Load Teleprinter and Print (TPC)

Transfers AC bits 4-11 to the TTO register and starts shifting the character out to the printer/punch units. This instruction does not clear the teleprinter flag. This instruction can be microprogrammed with TCF to produce TLS.

6YY5 Skip on Printer or Keyboard Flag (TSK)

Skips the next instruction if the keyboard flag or printer flag is set and the interrupt enable flip-

flop is set.

6YY6 Load Teleprinter Sequence (TLS)

This instruction combines TCF and TPC. The teleprinter flag is cleared and the contents of AC bits 4-11 are transferred to the TTO register where the hardware shifts the character out to the printer/punch unit. Then the shifting operation has finished outputting the character and is ready for another character, the teleprinter flag is set. The whole operation, from the time at which the TLS has cleared the flag and the TTO starts character transfer, until the time the hardware finishes with the character and again sets the flag, requires 100 milliseconds at 110 baud.

Since a Clear All Flags instruction or operation of the CLEAR button on the console will cause the teleprinter output flag to be cleared, it is necessary that each program set the flag by means of a TFL instruction before commencing a teleprinter output sequence for the first time.

In all of the above instructions the device code has been represented as XX for keyboard instructions and YY for teleprinter instructions. In the case of the console teleprinter, these would be device codes 03 and 04 respectively. For further information on device codes, consult Secion VII of this specification.

VII. Device Code Selection

All input/output devices on a PDP8/E (or other Family-of-8 machine) have device codes. These device codes determine which unique input/output device responds to a given instruction. In a typical I/O instruction, such as 6031, the "6" indicates that this is an I/O instruction; the"03"indicates that the device having device code 03 is the device that is to respond to the instruction; and the "1" determines exactly what type of input/output operation is to take place at device 03.

It is vitally necessary that no two input/output devices on the same PDP8/E system have the same device code. If, for example, two devices use code 03, the instruction 6031 would cause a skip on teleprinter receiver flag if either flag was set. Instruction 6036 would probably OR together the contents of both receiver input registers, even if one contained only a partially assembled character - so long as one of them had the receiver flag set. In summary, a multiple teleprinter system (or any multi-input/output device system) must have unique device codes for each device so that the program can address each device individually.

Since there are a limited number of possible device codes in a PDP8/E, no assignment of device codes for large multi-teleprinter systems can be made. It is suggested, however, that the following device codes be used first:

03/04 Console teleprinter receive/transmit
30/31 Second KL8/E teleprinter receive/transmit
32/33
34/35
36/37

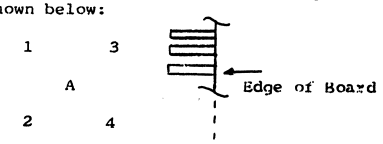
For PT08 compatibility 40/41,42/43,44/45,46/47 may be used, as long as no DP8-E Synchronous Modem Control is used.

To obtain additional device codes, determine which device codes you do not have yet on your system. Then write down the desired device code as two binary numbers, labelling the most significant bit "MD3", the next "MD4", the next"MD5", the next "MD6", the next "MD7", and the last "MD8". For example, for device code 03:

Octal:			0			3	
Binary:	0	0	0	0	1	1	
Label:	MD3	MD4	MD5	MD6	MD7	MD8	
Split Lug Group:	B	A	F	E	D	C	

The "Split Lug Groups" are explained on the next page.

In the lower right hand corner of the M8650/M8650YA board are split lugs which determine the device code to which the receiver will respond and the device code to which the transmitter will respond. The split lugs are arranged in groups of four. Each group has an alphabetic designation (A-F), and each split lug within a group has a numeric designation (1-4). A typical layout is shown below:



The correct strapping for each possible RECEIVER device code is given below:

	Group A	Group B	Group C	Group D	Group E	Group F
00	1-3	1-2	1-2	1-2	2-4	2-1
01	1-3	1-2	4-2	1-2	2-4	2-1
02	1-3	1-2	1-2	4-2	2-4	2-1
03	1-3	1-2	4-2	4-2	2-4	2-1
04	1-3	1-2	1-2	1-2	3-4	2-1
05	1-3	1-2	4-2	1-2	3-4	2-1
06	1-3	1-2	1-2	4-2	3-4	2-1
07	1-3	1-2	4-2	4-2	3-4	2-1
10	1-3	1-2	1-2	1-2	2-4	3-1
11	1-3	1-2	4-2	1-2	2-4	3-1
12	1-3	1-2	1-2	4-2	2-4	3-1
13	1-3	1-2	4-2	4-2	2-4	3-1
14	1-3	1-2	1-2	1-2	3-4	3-1
15	1-3	1-2	4-2	1-2	3-4	3-1
16	1-3	1-2	1-2	4-2	3-4	3-1
17	1-3	1-2	4-2	4-2	3-4	3-1
20	4-3	1-2	1-2	1-2	2-4	2-1
21	4-3	1-2	4-2	1-2	2-4	2-1
22	4-3	1-2	1-2	4-2	2-4	2-1
23	4-3	1-2	4-2	4-2	2-4	2-1
24	4-3	1-2	1-2	1-2	3-4	2-1
25	4-3	1-2	4-2	1-2	3-4	2-1
26	4-3	1-2	1-2	4-2	3-4	2-1
27	4-3	1-2	4-2	4-2	3-4	2-1

IMPORTANT NOTICE: Device codes 03 for receiver and 04 for transmitter are factory wired by means of machine inserted jumpers located in the split lug groups A,B,C,D,E,&F.
CUT THESE JUMPERS BEFORE ADDING THE JUMPERS LISTED ABOVE.

Continuation of receiver device code strapping table:

	Group A	Group B	Group C	Group D	Group E	Group F
30	4-3	1-2	1-2	1-2	2-4	3-1
31	4-3	1-2	4-2	1-2	2-4	3-1
32	4-3	1-2	1-2	4-2	2-4	3-1
33	4-3	1-2	4-2	4-2	2-4	3-1
34	4-3	1-2	1-2	1-2	3-4	3-1
35	4-3	1-2	4-2	1-2	3-4	3-1
36	4-3	1-2	1-2	4-2	3-4	3-1
37	4-3	1-2	4-2	4-2	3-4	3-1
40	1-3	4-2	1-2	1-2	2-4	2-1
41	1-3	4-2	4-2	1-2	2-4	2-1
42	1-3	4-2	1-2	4-2	2-4	2-1
43	1-3	4-2	4-2	4-2	2-4	2-1
44	1-3	4-2	1-2	1-2	3-4	2-1
45	1-3	4-2	4-2	1-2	3-4	2-1
46	1-3	4-2	1-2	4-2	3-4	2-1
47	1-3	4-2	4-2	4-2	3-4	2-1
50	1-3	4-2	1-2	1-2	2-4	3-1
51	1-3	4-2	4-2	1-2	2-4	3-1
52	1-3	4-2	1-2	4-2	2-4	3-1
53	1-3	4-2	4-2	4-2	2-4	3-1
54	1-3	4-2	1-2	1-2	3-4	3-1
55	1-3	4-2	4-2	1-2	3-4	3-1
56	1-3	4-2	1-2	4-2	3-4	3-1
57	1-3	4-2	4-2	4-2	3-4	3-1
60	4-3	4-2	1-2	1-2	2-4	2-1
61	4-3	4-2	4-2	1-2	2-4	2-1
62	4-3	4-2	1-2	4-2	2-4	2-1
63	4-3	4-2	4-2	4-2	2-4	2-1
64	4-3	4-2	1-2	1-2	3-4	2-1
65	4-3	4-2	4-2	1-2	3-4	2-1
66	4-3	4-2	1-2	4-2	3-4	2-1
67	4-3	4-2	4-2	4-2	3-4	2-1
70	4-3	4-2	1-2	1-2	2-4	3-1
71	4-3	4-2	4-2	1-2	2-4	3-1
72	4-3	4-2	1-2	4-2	2-4	3-1
73	4-3	4-2	4-2	4-2	2-4	3-1
74	4-3	4-2	1-2	1-2	3-4	3-1
75	4-3	4-2	4-2	1-2	3-4	3-1
76	4-3	4-2	1-2	4-2	3-4	3-1
77	4-3	4-2	4-2	4-2	3-4	3-1

IMPORTANT NOTICE: Device codes 03 and 04 for receiver and transmitter respectively are factory wired by means of machine inserted jumpers located in the split lug groups A,B,C,D,E,&F. CUT THESE JUMPERS BEFORE ADDING THE JUMPERS LISTED ABOVE.

The correct strapping for each possible TRANSMITTER device code is given below:

	Group A	Group B	Group C	Group D	Group E	Group F
00	1-2	1-3	1-3	1-3	2-1	2-4
01	1-2	1-3	4-3	1-3	2-1	2-4
02	1-2	1-3	1-3	4-3	2-1	2-4
03	1-2	1-3	4-3	4-3	2-1	2-4
04	1-2	1-3	1-3	1-3	3-1	2-4
05	1-2	1-3	4-3	1-3	3-1	2-4
06	1-2	1-3	1-3	4-3	3-1	2-4
07	1-2	1-3	4-3	4-3	3-1	2-4
10	1-2	1-3	1-3	1-3	2-1	3-4
11	1-2	1-3	4-3	1-3	2-1	3-4
12	1-2	1-3	1-3	4-3	2-1	3-4
13	1-2	1-3	4-3	4-3	2-1	3-4
14	1-2	1-3	1-3	1-3	3-1	3-4
15	1-2	1-3	4-3	1-3	3-1	3-4
16	1-2	1-3	1-3	4-3	3-1	3-4
17	1-2	1-3	4-3	4-3	3-1	3-4
	1					
20	4-2	1-3	1-3	1-3	2-1	2-4
21	4-2	1-3	4-3	1-3	2-1	2-4
22	4-2	1-3	1-3	4-3	2-1	2-4
23	4-2	1-3	4-3	4-3	2-1	2-4
24	4-2	1-3	1-3	1-3	3-1	2-4
25	4-2	1-3	4-3	1-3	3-1	2-4
26	4-2	1-3	1-3	4-3	3-1	2-4
27	4-2	1-3	4-3	4-3	3-1	2-4
30	4-2	1-3	1-3	1-3	2-1	3-4
31	4-2	1-3	4-3	1-3	2-1	3-4
32	4-2	1-3	1-3	4-3	2-1	3-4
33	4-2	1-3	4-3	4-3	2-1	3-4
34	4-2	1-3	1-3	1-3	3-1	3-4
35	4-2	1-3	4-3	1-3	3-1	3-4
36	4-2	1-3	1-3	4-3	3-1	3-4
37	4-2	1-3	4-3	4-3	3-1	3-4
40	1-2	4-3	1-3	1-3	2-1	2-4
41	1-2	4-3	4-3	1-3	2-1	2-4
42	1-2	4-3	1-3	4-3	2-1	2-4
43	1-2	4-3	4-3	4-3	2-1	2-4
44	1-2	4-3	1-3	1-3	3-1	2-4
45	1-2	4-3	4-3	1-3	3-1	2-4
46	1-2	4-3	1-3	4-3	3-1	2-4
47	1-2	4-3	4-3	4-3	3-1	2-4

Continuation of transmitter device code strapping table:

	Group A	Group B	Group C	Group D	Group E	Group F
50	1-2	4-3	1-3	1-3	2-1	3-4
51	1-2	4-3	4-3	1-3	2-1	3-4
52	1-2	4-3	1-3	4-3	2-1	3-4
53	1-2	4-3	4-3	4-3	2-1	3-4
54	1-2	4-3	1-3	1-3	3-1	3-4
55	1-2	4-3	4-3	1-3	3-1	3-4
56	1-2	4-3	1-3	4-3	3-1	3-4
57	1-2	4-3	4-3	4-3	3-1	3-4
60	4-2	4-3	1-3	1-3	2-1	2-4
61	4-2	4-3	4-3	1-3	2-1	2-4
62	4-2	4-3	1-3	4-3	2-1	2-4
63	4-2	4-3	4-3	4-3	2-1	2-4
64	4-2	4-3	1-3	1-3	3-1	2-4
65	4-2	4-3	4-3	1-3	3-1	2-4
66	4-2	4-3	1-3	4-3	3-1	2-4
67	4-2	4-3	4-3	4-3	3-1	2-4
70	4-2	4-3	1-3	1-3	2-1	3-4
71	4-2	4-3	4-3	1-3	2-1	3-4
72	4-2	4-3	1-3	4-3	2-1	3-4
73	4-2	4-3	4-3	4-3	2-1	3-4
74	4-2	4-3	1-3	1-3	3-1	3-4
75	4-2	4-3	4-3	1-3	3-1	3-4
76	4-2	4-3	1-3	4-3	3-1	3-4
77	4-2	4-3	4-3	4-3	3-1	3-4

It will be noted that in many cases two straps are inserted in the same split lug. This is acceptable, but three in the same lug would not be, nor would a diagonal run such as from lug 1 to 4 or from lug 2 to 3. If such runs exist, the strapping has been done incorrectly.

VIII. Speed Selection

A group of split lugs labelled "G" determine the operating speed of each KL8/E, EA, EB etc. option. Another split lug group labelled "H" determines whether the transmitter and receiver sections operate at the same speed. The correct strappings of groups G & H are listed below for each option:

Option	Group G	Group H	Notes
KL8/E	7-8	1-2	M8650 board
KL8/EA	7-8	1-2	M8650 board
KL8/EB	7-8	1-2	M8650 YA board
KL8/EC	5-6	1-2	M8650 YA board
KL8/ED	3-4	1-2	M8650 YA board
KL8/EE	1-2	1-2	M8650 YA board
KL8/EF	7-8	2-3	M8650 YA board
KL8/EG	7-8	H2 to G5	M8650 YA board

IMPORTANT NOTICE: There are no factory machine inserted jumpers in Group G. There must be one and only one of the straps shown in the above table in place in section G for the board to work; said jumper was hand soldered between the split lugs at the time the board left Digital's production facility. Remove that jumper before adding any other Group G jumpers. Group H has a factory machine inserted jumper between H1 and H2. Cut this jumper before adding any other Group H jumper.

IX. Stop Code Selection

Mechanical teleprinters, such as those that operate at 110 baud, require stop bits after each character transmitted so that their mechanisms can coast to a predetermined starting position before handling the next character. The same restriction applies to their receivers. To prevent the KL8/E from sending characters during this stopping interval, a stop bit counter is inserted in the KL8/E transmitter circuitry. This counter permits the KL8/E to request another character from the program as soon as it has send the last information bit of the preceding character but prohibits it from sending that new character until an appropriate stop bit interval has been counted out following the transmission of the final information bit of the preceding character. This counter is controlled by a split lug group labelled "J".

Group J	Stop Code	Devices Using This Stop Code
1-2	1 bit	Electronic receiver devices operating at 150 baud and above.
2-3	2 bits	Mechanical receiver devices operating at 110 baud.

The KL8/E and KL8/EA contain a machine inserted jumper

that provides 2 stop bits (J2-J3), as 110 baud devices use 2 stop bits. To the best of the author's knowledge, all devices operating at speeds above 110 baud use electronic receiver systems (even though all other parts of the device may be mechanical), so the KL8/EB, EC, etc are provided with hand inserted jumpers from J1 to J2, thus providing only 1 stop bit.

X. Special Notes

In the upper right corner of schematic E-CS-M8650-0-1, one will find points labelled E, H, and M. These, as indicated in the notes on the cover sheet,are designations of pins on the forty pin header at which point cables connect to the M8650 printed circuit board. Pin E is the input to the M8650 TTL logic circuitry in the receiver section. Pin H is the output of a filter and Schmidt Trigger circuit which convert 20 milliampere signals from the teleprinter keyboard to TTL logic signals. Pin M is the output of an inverter and EIA/CCITT level converter that convert EIA/CCITT received signals to TTL logic signals. The cable that is used for serving 20 milliampere devices (7008360) consists of a Mate-N-Lock connector at one end and a 40 pin housing at the other. The 40 pin housing contains a jumper from pin E to pin H, so that when that cable is plugged into the 40 pin header, a connection will be established from the 20 milliampere receiving circuitry to the receiving circuitry of the M8650. The cables that can be used with EIA/CCITT interface devices (BC01V and BC05C) consist of a 25-pin male connector at one end and a 40 pin housing at the other. In this housing there is a jumper from pin E to pin M, so that when this cable is plugged into the forty pin header, a connection will be established from the EIA/CCITT receiving circuitry to the receiving circuitry of the M8650 board.

It should be noted that the 175 ohm limitation cited for Reader Run control is actually unimportant, as the keyboard and printer requirements of 150 ohm limitation on line resistance are the ruling limitations.